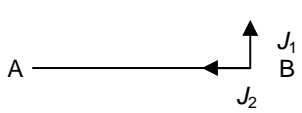
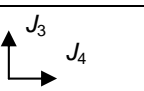


1(i)	$m = \frac{4}{3}\pi r^3 \rho$	M1	Expression for $m$	
	$\frac{dm}{dt} = 4\pi r^2 \rho \frac{dr}{dt}$	M1	Relate $\frac{dm}{dt}$ to $\frac{dr}{dt}$	
	$\lambda \cdot 4\pi r^2 = 4\pi r^2 \rho \frac{dr}{dt}$	M1	Use of $\frac{dm}{dt}$ proportional to surface area	
	$\frac{dr}{dt} = \frac{\lambda}{\rho} = k$	E1	Accept alternative symbol for constant if used correctly (here and subsequently)	
	$r = r_0 + kt$	M1	Integrate and use condition	
	$m = \frac{4}{3}\pi \rho (r_0 + kt)^3$	A1		
				6
(ii)	$\frac{d}{dt}(mv) = mg$	M1	N2L	
	$mv = \int mg \, dt = \int \frac{4}{3}\pi \rho (r_0 + kt)^3 g \, dt$	M1	Express $mv$ as an integral	
	$= \frac{4}{3}\pi \rho g \left[ \frac{1}{4k} (r_0 + kt)^4 + c \right]$	M1	Integrate	
	$t = 0, v = 0 \Rightarrow c = -\frac{1}{4k} r_0^4$	M1	Use condition	
	$\frac{4}{3}\pi \rho (r_0 + kt)^3 v = \frac{4}{3}\pi \rho g \cdot \frac{1}{4k} \left[ (r_0 + kt)^4 - r_0^4 \right]$	M1	Substitute for $m$	
	$v = \frac{g}{4k} \left[ r_0 + kt - \frac{r_0^4}{(r_0 + kt)^3} \right]$	A1		
				6
2(i)	$AP = 2a \cos \theta$	M1	Attempt AP in terms of $\theta$	
	$PB = \frac{5}{2}a - 2a \cos \theta$	E1		
	$V = -mg \cdot PB - mg \cdot PA \cos \theta$	M1	Attempt $V$ in terms of $\theta$	
	$= -mg \left( \frac{5}{2}a - 2a \cos \theta \right) - mg (2a \cos \theta) \cos \theta$			
	$= -mga \left( 2 \cos^2 \theta - 2 \cos \theta + \frac{5}{2} \right)$	E1		
				4
(ii)	$\frac{dV}{d\theta} = mga \sin \theta (4 \cos \theta - 2)$	M1	Differentiate	
	$\frac{dV}{d\theta} = 0 \Rightarrow \sin \theta = 0$ or $\cos \theta = \frac{1}{2}$	M1	Solve	
	$\Rightarrow \theta = 0$ or $\pm \frac{1}{3}\pi$	A1	For 0 and either of $\frac{1}{3}\pi$ or $-\frac{1}{3}\pi$	
	$\frac{d^2V}{d\theta^2} = mga \sin \theta (-4 \sin \theta) + mga \cos \theta (4 \cos \theta - 2)$	M1	Differentiate again	
		A1		
	$\theta = 0 \Rightarrow \frac{d^2V}{d\theta^2} = 2mga > 0 \Rightarrow$ stable	M1	Consider sign of $V''$ in one case	
		F1	Correct deduction for one value of $\theta$	
	$\theta = \pm \frac{1}{3}\pi \Rightarrow \frac{d^2V}{d\theta^2} = -3mga < 0 \Rightarrow$ unstable	F1	Correct deduction for another value of $\theta$	
			N.B. Each F mark is dependent on both M marks. To get both F marks, the two values of $\theta$ must be physically possible (i.e. in the first or fourth quadrant) and not be equivalent or symmetrical positions.	
				8

3(i)	$P = Fv = mv \frac{dv}{dx} v$	M1	Use of $P = Fv$	
	$v^2 \frac{dv}{dx} = 0.0004(10000v + v^3)$	A1	Or equivalent	
	$\int \frac{v}{10000 + v^2} dv = \int 0.0004 dx$	M1	Separate variables	
	$\frac{1}{2} \ln  10000 + v^2  = 0.0004x + c$	M1	Integrate	
	$v^2 = Ae^{0.0008x} - 10000$	M1	Rearrange	
	$x = 0, v = 0 \Rightarrow A = 10000$	M1	Use condition	
	$v = 100\sqrt{e^{0.0008x} - 1}$	A1		
	$x = 900 \Rightarrow v = 102.7 > 80$ so successful			
	or $v = 80 \Rightarrow x = 618.37 < 900$ so successful	E1	Show that their $v$ implies successful take off	
				8
(ii)	$v \frac{dv}{dt} = 0.0004(10000v + v^3)$	F1	Follow previous DE	
	$\int \frac{1}{10000 + v^2} dv = \int 0.0004 dt$	M1	Separate variables	
	$\frac{1}{100} \tan^{-1}\left(\frac{1}{100}v\right) = 0.0004t + k$	M1	Integrate	
		A1		
	$t = 0, v = 0 \Rightarrow k = 0$	M1	Use condition	
	$\Rightarrow v = 100 \tan(0.04t)$	E1	Clearly shown	
	$v \rightarrow \infty$ at finite time suggests model invalid	B1		
				7
(iii)	$t = 11 \Rightarrow v = 47.0781$	B1	At least 3sf	
	Hence maximum $P = 230.049m$	M1	Attempt to calculate maximum $P$	
	$v = 47.0781 \Rightarrow x = 250.237$	M1	Use solution in (i) to calculate $x$	
	$v^2 \frac{dv}{dx} = 230.049$	M1	Set up DE for $t \geq 11$ . Constant acceleration formulae $\Rightarrow$ M0.	
	$\frac{1}{3}v^3 = 230.049x + B$	M1	Separate variables and integrate	
		F1	Follow their maximum $P$ (condone no constant)	
	$v = 47.0781, x = 250.237 \Rightarrow B = -22786.3$	M1	Use condition on $x, v$ (not $v = 0$ , not $x = 0$ unless clearly compensated for when making conclusion). Constant acceleration formulae $\Rightarrow$ M0.	
	$v = 80 \Rightarrow x = 840.922$ or $x = 900 \Rightarrow v = 82.0696$	M1	Relevant calculation. Must follow solving a DE.	
	so successful	A1	All correct (accept 2sf or more)	
				9

4(i)	Considering elements of length $\delta x \Rightarrow I = \int_0^{2a} \rho x^2 dx$	M1	Set up integral	
	$= \frac{M}{8a^2} \int_0^{2a} (5ax^2 - x^3) dx$	M1	Substitute for $\rho$ in predominantly correct integral	
	$= \frac{M}{8a^2} \left[ \frac{5}{3} ax^3 - \frac{1}{4} x^4 \right]_0^{2a}$	M1	Integrate	
	$= \frac{7}{6} Ma^2$	E1		
	Considering elements of length $\delta x \Rightarrow M\bar{x} = \int_0^{2a} \rho x dx$	M1	Set up integral	
	$= \frac{M}{8a^2} \int_0^{2a} (5ax - x^2) dx$	M1	Substitute for $\rho$ in predominantly correct integral	
	$= \frac{M}{8a^2} \left[ \frac{5}{2} ax^2 - \frac{1}{3} x^3 \right]_0^{2a}$	M1	Integrate	
	$\bar{x} = \frac{11}{12} a$	E1		
				8
(ii)	$\frac{1}{2} I \dot{\theta}^2 = Mg \cdot \frac{11}{12} a (1 - \cos \theta)$	M1	KE term in terms of angular velocity	
		B1	$\pm Mg \cdot \frac{11}{12} a \cos \theta$ seen	
		M1	energy equation	
	$\dot{\theta} = \sqrt{\frac{11g}{7a} (1 - \cos \theta)}$	A1		
				4
(iii)		F1	Their $\dot{\theta}$ at $\theta = \frac{1}{2}\pi$	
	$\theta = \frac{1}{2}\pi \Rightarrow \dot{\theta} = \sqrt{\frac{11g}{7a}}$	M1	Use of angular momentum	
	$2a \cdot (-J_1) = I \left( 0 - \sqrt{\frac{11g}{7a}} \right)$	A1	Correct equation (their $\dot{\theta}$ )	
	$J_1 = \frac{1}{12} M \sqrt{77ag}$	E1		
	$J_2 = \frac{1}{12} M \sqrt{77ag}$	B1	Correct answer or follow their $J_1$	
				5
(iv)		M1	Consider horizontal impulses	
	$J_4 = J_2$ $= \frac{1}{12} M \sqrt{77ag}$	F1	Follow their $J_2$	
	$J_3 + J_1 = M \cdot \frac{11}{12} a \sqrt{\frac{11g}{7a}}$	M1	Vertical impulse-momentum equation	
		M1	Use of $r\dot{\theta}$	
	$J_3 = \frac{1}{21} M \sqrt{77ag}$	A1	cao	
	angle = $\tan^{-1} \left( \frac{J_3}{J_4} \right) = \tan^{-1} \left( \frac{\frac{1}{21} M \sqrt{77ag}}{\frac{1}{12} M \sqrt{77ag}} \right)$	M1	Must substitute	
	$= \tan^{-1} \left( \frac{4}{7} \right) \approx 0.519 \text{ rad} \approx 29.7^\circ$	A1	cao (any correct form)	
				7

1(i) $x = PB$ $x = \sqrt{a^2 + y^2}$ $V = \frac{1}{2}kx^2 - mgy$ $= \frac{1}{2}k(a^2 + y^2) - mgy$	M1 May be implied A1 M1 EPE term M1 GPE term A1 cao	5
(ii) $\frac{dV}{dy} = ky - mg$ equilibrium $\Rightarrow \frac{dV}{dy} = 0$ $\Rightarrow y = \frac{mg}{k}$ $\frac{d^2V}{dy^2} = k > 0$ $\Rightarrow$ stable	M1 Differentiate their $V$ B1 Seen or implied A1 cao M1 Consider sign of $V''$ (or $V'$ either side) E1 Complete argument	5
(iii) $R = T \sin \hat{PBA} = k \cdot PB \cdot \frac{a}{PB}$ $= ka$	M1 Use Hooke's law and resolve A1	2
2(i) $\frac{d}{dt}(mv) = 0 \Rightarrow mv$ constant hence $mv = m_0u$ $\frac{dm}{dt} = k$ $\Rightarrow m = m_0 + kt$ $v = \frac{m_0u}{m} = \frac{m_0u}{m_0 + kt}$ $x = \int \frac{m_0u}{m_0 + kt} dt$ $= \frac{m_0u}{k} \ln(m_0 + kt) + A$ $x = 0, t = 0 \Rightarrow A = -\frac{m_0u}{k} \ln m_0$ $x = \frac{m_0u}{k} \ln \left( \frac{m_0 + kt}{m_0} \right)$	M1 Or no external forces $\Rightarrow$ momentum conserved, or attempt using $\delta$ terms. A1 B1 $\frac{dm}{dt} = k$ seen B1 $m_0 + kt$ stated or clearly used as mass E1 Complete argument (dependent on all previous marks and $m_0 + kt$ derived, not just stated) M1 Integrate $v$ A1 cao M1 Use condition A1 cao	9
(ii) $v = \frac{1}{2}u \Rightarrow m_0 + kt = 2m_0$ $\Rightarrow x = \frac{m_0u}{k} \ln \left( \frac{2m_0}{m_0} \right)$ $\Rightarrow x = \frac{m_0u}{k} \ln 2$	M1 Attempt to calculate value of $m$ or $t$ M1 Substitute their $m$ or $t$ into $x$ F1 $t = \frac{m_0}{k}$ or $m = 2m_0$ in their $x$	3

3(i) $I = \int_{-a}^a \rho x^2 dx$ $\rho = \frac{m}{2a}$ $I = \frac{m}{2a} \left[ \frac{1}{3} x^3 \right]_{-a}^a$ $= \frac{1}{6} ma^2 - -\frac{1}{6} ma^2$ $\frac{1}{3} ma^2$	M1 Set up integral A1 Or equivalent M1 Use mass per unit length in integral or $I$ M1 Integrate M1 Use limits E1 Complete argument <div style="text-align: right; border: 1px solid black; width: 20px; float: right;">6</div>
(ii) $I_{\text{rod}} = \frac{1}{3} \times 1.2 \times 0.4^2 + 1.2 \times 0.4^2$ $I_{\text{sphere}} = \frac{2}{5} \times 2 \times 0.1^2 + 2 \times 0.9^2$ $I = I_{\text{rod}} + I_{\text{sphere}} = 1.884$	M1 Use $\frac{1}{3} ma^2$ or $\frac{4}{3} ma^2$ A1 Rod term(s) all correct M1 Use formula for sphere M1 Use parallel axis theorem A1 Sphere terms all correct M1 Add moment of inertia for rod and sphere A1 cao <div style="text-align: right; border: 1px solid black; width: 20px; float: right;">7</div>
(iii) $\frac{1}{2} I \dot{\theta}^2 - 1.2g \times 0.4 \cos \theta - 2g \times 0.9 \cos \theta$ $= -1.2g \times 0.4 \cos \alpha - 2g \times 0.9 \cos \alpha$ $\dot{\theta}^2 = \frac{4.56g}{1.884} (\cos \theta - \cos \alpha)$	M1 Use energy M1 KE term M1 Reasonable attempt at GPE terms A1 All terms correct (but ignore signs) M1 Rearrange F1 Only follow an incorrect $I$ <div style="text-align: right; border: 1px solid black; width: 20px; float: right;">6</div>
(iv) $2\dot{\theta}\ddot{\theta} = \frac{4.56g}{1.884} (-\sin \theta \dot{\theta})$ or $I\ddot{\theta} = -1.2g \times 0.4 \sin \theta - 2g \times 0.9 \sin \theta$ $\sin \theta \approx \theta \Rightarrow \ddot{\theta} = -11.86\theta$ i.e. SHM $T \approx \frac{2\pi}{\sqrt{11.86}} \approx 1.82$	M1 Differentiate, or use moment = $I\ddot{\theta}$ F1 Equation for $\ddot{\theta}$ (only follow their $I$ or $\dot{\theta}^2$ ) M1 Use small angle approximation (in terms of $\theta$ ) E1 All correct (for their $I$ ) and make conclusion F1 $\frac{2\pi}{\text{their } \omega}$ <div style="text-align: right; border: 1px solid black; width: 20px; float: right;">5</div>

<p>4(i) <math>2v \frac{dv}{dx} = 2 - 8v^2</math></p> $\int \frac{v}{1-4v^2} dv = \int dx$ $-\frac{1}{8} \ln  1-4v^2  = x + c_1$ $x = 0, v = 0 \Rightarrow c_1 = 0$ $1-4v^2 = e^{-8x}$ $v^2 = \frac{1}{4}(1-e^{-8x})$	<p>M1 N2L A1 M1 Separate A1 LHS M1 Use condition M1 Rearrange E1 Complete argument</p>	7
<p>(ii) <math>F = 2 - 8v^2 = 2 - 2(1 - e^{-8x})</math></p> $= 2e^{-8x}$ <p>Work done = <math>\int_0^2 F dx</math></p> $= \int_0^2 2e^{-8x} dx$ $= \left[ -\frac{1}{4}e^{-8x} \right]_0^2$ $= \frac{1}{4}(1 - e^{-16})$	<p>M1 Substitute given <math>v^2</math> into <math>F</math> A1 cao M1 Set up integral of <math>F</math> A1 cao M1 Integrate A1 Accept <math>\frac{1}{4}</math> or 0.25 from correct working</p>	6
<p>(iii) <math>2 \frac{dv}{dt} = 2 - 8v^2</math></p> $\frac{1}{4} \int \frac{1}{\frac{1}{4} - v^2} dv = \int dt$ $\frac{1}{4} \ln \left  \frac{\frac{1}{2} + v}{\frac{1}{2} - v} \right  = t + c_2$ $t = 0, v = 0 \Rightarrow c_2 = 0$ $\frac{\frac{1}{2} + v}{\frac{1}{2} - v} = e^{4t}$ $1 + 2v = e^{4t}(1 - 2v)$ $2v(1 + e^{4t}) = e^{4t} - 1$ $v = \frac{1}{2} \left( \frac{e^{4t} - 1}{e^{4t} + 1} \right) = \frac{1}{2} \left( \frac{1 - e^{-4t}}{1 + e^{-4t}} \right)$	<p>M1 N2L M1 Separate A1 LHS M1 Use condition M1 Rearrange (remove log) M1 Rearrange (<math>v</math> in terms of <math>t</math>) E1 Complete argument</p>	7
<p>(v) <math>t = 1 \Rightarrow v = 0.4820</math> <math>t = 2 \Rightarrow v = 0.4997</math> Impulse = <math>mv_2 - mv_1</math> <math>= 0.0353</math></p>	<p>B1 B1 M1 Use impulse-momentum equation A1 Accept anything in interval [0.035, 0.036]</p>	4

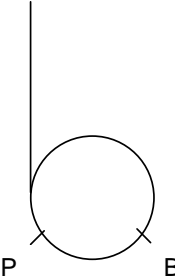
## 4764 Mechanics 4

<p>1(i) If <math>\delta m</math> is change in mass over time <math>\delta t</math>  PCLM <math>mv = (m + \delta m)(v + \delta v) +  \delta m (v - u)</math> [N.B.  <math>\delta m &lt; 0</math>]</p> $(m + \delta m) \frac{\delta v}{\delta t} + u \frac{\delta m}{\delta t} = 0 \Rightarrow m \frac{dv}{dt} = -u \frac{dm}{dt}$ $\frac{dm}{dt} = -k \Rightarrow m = m_0 - kt$ $\Rightarrow (m_0 - kt) \frac{dv}{dt} = uk$	<p>M1 Change in momentum over time <math>\delta t</math>  M1 Rearrange to produce DE  A1 Accept sign error  M1 Find <math>m</math> in terms of <math>t</math>  E1 Convincingly shown</p>	5
<p>(ii)</p> $v = \int \frac{uk}{m_0 - kt} dt$ $= -u \ln(m_0 - kt) + c$ $t = 0, v = 0 \Rightarrow c = u \ln m_0$ $v = u \ln \left( \frac{m_0}{m_0 - kt} \right)$	<p>M1 Separate and integrate  A1 cao (allow no constant)  M1 Use initial condition  A1 All correct</p>	4
<p>(iii) <math>m = \frac{1}{3}m_0 \Rightarrow m_0 - kt = \frac{1}{3}m_0</math>  <math>\Rightarrow v = u \ln 3</math></p>	<p>M1 Find expression for mass or time  A1 Or <math>t = 2m_0 / 3k</math>  A1</p>	3

<p>2(i) <math>P = Fv</math>  <math>= mv \frac{dv}{dx} v</math>  <math>\Rightarrow mv^2 \frac{dv}{dx} = m(k^2 - v^2)</math>  <math>\Rightarrow \frac{v^2}{k^2 - v^2} \frac{dv}{dx} = 1</math>  <math>\Rightarrow \left( \frac{k^2}{k^2 - v^2} - 1 \right) \frac{dv}{dx} = 1</math>  <math>\int \left( \frac{k^2}{k^2 - v^2} - 1 \right) dv = \int dx</math>  <math>\frac{1}{2} k \ln \left( \frac{k+v}{k-v} \right) - v = x + c</math>  <math>x = 0, v = 0 \Rightarrow c = 0</math>  <math>x = \frac{1}{2} k \ln \left( \frac{k+v}{k-v} \right) - v</math></p>	<p>M1 Used, not just quoted  M1 Use N2L and expression for acceleration  A1 Correct DE  M1 Rearrange  E1 Convincingly shown  M1 Separate and integrate  A1 LHS  M1 Use condition  A1 cao</p>	9
<p>(ii) Terminal velocity when acceleration zero  <math>\Rightarrow v = k</math>  <math>v = 0.9k \Rightarrow x = \frac{1}{2} k \ln \left( \frac{1.9}{0.1} \right) - 0.9k = \left( \frac{1}{2} \ln 19 - 0.9 \right) k \approx 0.572k</math></p>	<p>M1  A1  F1 Follow their solution to (i)</p>	3

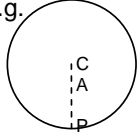
<p>3(i) <math>M = \int_0^a k(a+r)2\pi r \, dr</math>  <math>= 2k\pi \left[ \frac{1}{2}ar^2 + \frac{1}{3}r^3 \right]_0^a</math>  <math>= \frac{5}{3}k\pi a^3</math>  <math>I = \int_0^a k(a+r)2\pi r \cdot r^2 \, dr</math>  <math>= 2k\pi \left[ \frac{1}{4}ar^4 + \frac{1}{5}r^5 \right]_0^a</math>  <math>= \frac{9}{10}k\pi a^5</math>  <math>= \frac{27}{50}Ma^2</math></p>	<p>M1 Use circular elements (for <math>M</math> or <math>I</math>)  M1 Integral for mass  M1 Integrate (for <math>M</math> or <math>I</math>)  A1 For [...]  E1  M1 Integral for <math>I</math>  A1 For [...]  A1 cao  E1 Complete argument (including mass)</p>	9
<p>(ii) <math>I = 13.5</math>  <math>0.625 \times 50 = I\omega</math>  <math>\Rightarrow \omega \approx 2.31</math></p>	<p>B1 Seen or used (here or later)  M1 Use angular momentum  M1 Use moment of impulse  A1 cao</p>	4
<p>(iii) <math>\ddot{\theta} = \frac{30 - 2.31}{20} \approx 1.38</math>  Couple = <math>I\ddot{\theta}</math>  <math>\approx 18.7</math></p>	<p>M1 Find angular acceleration  M1 Use equation of motion  F1 Follow their <math>\omega</math> and <math>I</math></p>	3
<p>(iv) <math>I\ddot{\theta} = -3\dot{\theta}</math>  <math>I \frac{d\dot{\theta}}{dt} = -3\dot{\theta}</math>  <math>\int \frac{d\dot{\theta}}{\dot{\theta}} = \int -\frac{3}{I} dt</math>  <math>\ln \dot{\theta}  = -\frac{t}{4.5} + c</math>  <math>\dot{\theta} = Ae^{-t/4.5}</math>  <math>t = 0, \dot{\theta} = 30 \Rightarrow A = 30</math>  <math>\dot{\theta} = 30e^{-t/4.5}</math></p>	<p>B1 Allow sign error and follow their <math>I</math> (but not <math>M</math>)  M1 Set up DE for <math>\dot{\theta}</math> (first order)  M1 Separate and integrate  B1 <math>\ln(\text{multiple of } \dot{\theta})</math> seen  M1 Rearrange, dealing properly with constant  M1 Use condition on <math>\dot{\theta}</math>  A1</p>	7
<p>(v) Model predicts <math>\dot{\theta}</math> never zero in finite time.</p>	<p>B1</p>	1



<p>4(i) <math>V = \frac{1}{2} \left( \frac{mg}{10a} \right) (a\theta)^2 + mga \cos \theta</math> (relative to centre of pulley)</p> <p><math>\frac{dV}{d\theta} = \frac{1}{2} \left( \frac{mg}{10a} \right) \cdot 2a^2\theta - mga \sin \theta</math></p> <p><math>\frac{dV}{d\theta} = mga \left( \frac{1}{10}\theta - \sin \theta \right)</math></p>	<p>M1 EPE term</p> <p>B1 Extension = <math>a\theta</math></p> <p>M1 GPE relative to any zero level</p> <p>A1 (<math>\pm</math> constant)</p> <p>M1 Differentiate</p> <p>E1</p>	6
<p>(ii) <math>\theta = 0 \Rightarrow \frac{dV}{d\theta} = mga \left( \frac{1}{10}(0) - \sin 0 \right) = 0</math></p> <p>hence equilibrium</p> <p><math>\frac{d^2V}{d\theta^2} = mga \left( \frac{1}{10} - \cos \theta \right)</math></p> <p><math>V''(0) = -0.9mga &lt; 0</math></p> <p>hence unstable</p>	<p>M1 Consider value of <math>\frac{dV}{d\theta}</math></p> <p>E1</p> <p>M1 Differentiate again</p> <p>A1</p> <p>M1 Consider sign of <math>V''</math></p> <p>E1 <math>V''</math> must be correct</p>	6
<p>(iii) If the pulley is smooth, then the tension in the string is constant. Hence the EPE term is valid.</p>	<p>B1</p> <p>B1</p>	2
<p>(iv) Equilibrium positions at <math>\theta = 2.8</math>, <math>\theta = 7.1</math> and <math>\theta = 8.4</math></p> <p>From graph, <math>V''(2.8) = mga f'(2.8) &gt; 0</math> hence stable at <math>\theta = 2.8</math></p> <p><math>V''(7.1) = mga f'(7.1) &lt; 0 \Rightarrow</math> unstable at <math>\theta = 7.1</math></p> <p><math>V''(8.4) = mga f'(8.4) &gt; 0 \Rightarrow</math> stable at <math>\theta = 8.4</math></p>	<p>B1 One correct</p> <p>B1 All three correct, no extras Accept answers in [2.7,3.0], [7,7.2], [8.3,8.5]</p> <p>M1 Consider sign of <math>V''</math> or <math>f'</math></p> <p>A1</p> <p>A1 Accept no reference to <math>V''</math> for one conclusion but other two must relate to sign of <math>V''</math>, not just <math>f'</math>.</p> <p>A1</p>	6
<p>(v)</p> 	<p>B1 P in approximately correct place</p> <p>B1 B in approximately correct place</p>	2
<p>(vi) If <math>\theta &lt; 0</math> then expression for EPE not valid hence not necessarily an equilibrium position.</p>	<p>M1</p> <p>A1</p>	2

## 4764 MEI Mechanics 4

<p>1(i) <math>\frac{d}{dt}(mv) = mg</math>  <math>\Rightarrow \frac{dm}{dt}v + m\frac{dv}{dt} = mg</math>  <math>\Rightarrow \frac{mg}{2(v+1)}v + m\frac{dv}{dt} = mg</math>  <math>\Rightarrow \frac{dv}{dt} = g\left(1 - \frac{v}{2(v+1)}\right) = g\left(\frac{v+2}{2(v+1)}\right)</math>  <math>\Rightarrow \left(\frac{v+1}{v+2}\right)\frac{dv}{dt} = \frac{1}{2}g</math>  <math>\Rightarrow \left(1 - \frac{1}{v+2}\right)\frac{dv}{dt} = \frac{1}{2}g</math></p>	<p>B1 Seen or implied  M1 Expand  M1 Use <math>\frac{dm}{dt} = \frac{mg}{2(v+1)}</math>  M1 Separate variables (oe)  E1</p>	5
<p>(ii) <math>\int \left(1 - \frac{1}{v+2}\right) dv = \int \frac{1}{2}g dt</math>  <math>v - \ln v+2  = \frac{1}{2}gt + c</math>  <math>t = 0, v = 0 \Rightarrow -\ln 2 = c</math>  <math>v - \ln v+2  = \frac{1}{2}gt - \ln 2</math>  <math>t = \frac{2}{g}(v - \ln v+2  + \ln 2)</math>  <math>v = 10 \Rightarrow t \approx 1.68</math></p>	<p>M1 Integrate  A1 LHS  M1 Use condition  A1  B1</p>	5
<p>(iii) As <math>t</math> gets large, <math>v</math> gets large  So <math>\frac{dv}{dt} \rightarrow \frac{1}{2}g</math> (i.e. constant)</p>	<p>M1  A1 Complete argument</p>	2
<p>2(i) <math>V = -mg \cdot 2a \sin \theta + \frac{1}{2}mg(4a \sin \theta - a)^2</math>  <math>\frac{dV}{d\theta} = -2mga \cos \theta + \frac{mg}{2a}(4a \sin \theta - a) \cdot 4a \cos \theta</math>  <math>= -2mga \cos \theta + 2mga \cos \theta (4 \sin \theta - 1)</math>  <math>= 4mga \cos \theta (2 \sin \theta - 1)</math></p>	<p>B1 GPE  M1 Reasonable attempt at EPE  A1 EPE correct  M1 Differentiate  E1 Complete argument</p>	5
<p>(ii) <math>\frac{dV}{d\theta} = 0</math>  <math>\Leftrightarrow \cos \theta = 0</math> or <math>\sin \theta = \frac{1}{2}</math>  <math>\Leftrightarrow \theta = \frac{1}{2}\pi</math> or <math>\frac{1}{6}\pi</math>  <math>\frac{d^2V}{d\theta^2} = 4mga \cos \theta (2 \cos \theta) - 4mga \sin \theta (2 \sin \theta - 1)</math>  <math>V''\left(\frac{1}{2}\pi\right) (= -4mga) &lt; 0 \Rightarrow</math> unstable  <math>V''\left(\frac{1}{6}\pi\right) (= 4mga \cdot \frac{\sqrt{3}}{2}(\sqrt{3})) &gt; 0 \Rightarrow</math> stable</p>	<p>M1 Set derivative to zero  M1 Solve  A1 Both  M1 Second derivative (or alternative method)  M1 Consider sign  A1 One correct conclusion validly shown  A1 Complete argument</p>	7

<p>3(i) Mass of 'ring' <math>\approx 2\pi r \rho p</math>  <math>\Rightarrow I_C = \int_0^a r^2 \cdot 2\pi r \rho dr</math>  <math>= \left[ 2\pi \rho \cdot \frac{1}{4} r^4 \right]_0^a = \frac{1}{2} \pi a^4 \rho</math>  <math>M = \pi a^2 \rho</math>  <math>\Rightarrow I_C = \frac{1}{2} M a^2</math></p>	<p>B1 May be implied                      M1 Set up integral                      A1 All correct                      M1 Integrate                      M1 Use relationship between <math>\rho</math> and <math>M</math>                      E1 Complete argument</p>	6
<p>(ii) <math>I_A = I_C + M \left( \frac{1}{10} a \right)^2</math>  <math>= \frac{1}{2} M a^2 + \frac{1}{100} M a^2 = 0.51 M a^2</math></p>	<p>M1 Use parallel axis theorem                      E1 Convincingly shown</p>	2
<p>(iii) <math>I_A \ddot{\theta} = -Mg \cdot \frac{1}{10} a \sin \theta</math>  <math>\Rightarrow \ddot{\theta} = -\frac{g}{5.1a} \sin \theta</math>  <math>\theta</math> small <math>\Rightarrow \sin \theta \approx \theta</math>  <math>\Rightarrow \ddot{\theta} = -\frac{g}{5.1a} \theta</math>, i.e. SHM                      Period <math>2\pi \sqrt{\frac{5.1a}{g}} \approx 4.53 \sqrt{a}</math></p>	<p>B1 LHS                      B1 RHS                      M1 Expression for <math>\ddot{\theta}</math>                      M1 Use small angle approximation                      E1 Complete argument and conclude SHM                      F1 Follow their SHM equation</p>	6
<p>(iv) e.g.   <math>mg \cdot \frac{9}{10} a = Mg \cdot \frac{1}{10} a</math>  <math>\Rightarrow m = \frac{1}{9} M</math>  <math>I = 0.51 M a^2 + m \left( \frac{9}{10} a \right)^2</math>  <math>= 0.6 M a^2</math></p>	<p>B1 Show PAC in straight line (in any direction)                      M1 Moments or <math>(\sum m_i) \bar{x} = \sum m_i x_i</math> (oe)                      A1 Method may be implied                      M1                      E1 Convincingly shown</p>	5
<p>(v) <math>KE = \frac{1}{2} I \omega^2 = \frac{1}{2} (0.6 M a^2) \omega^2</math>  <math>= 0.3 M a^2 \omega^2</math>  <math>C \cdot \omega \cdot 2\pi = 0.3 M a^2 \omega^2</math>  <math>\Rightarrow C = \frac{0.3 M a^2 a \omega^2}{2\pi \omega}</math></p>	<p>M1 Attempt to find KE                      A1                      M1 Work-energy equation                      A1 Correct equation                      A1</p>	5

<p>4(i) At terminal velocity, <math>\Sigma F = 0 \Rightarrow k \cdot 60^2 = 90g</math>  <math>\Rightarrow k = \frac{1}{40}g</math></p>	<p>M1 Equilibrium of forces                      E1 Convincingly shown</p>	2
<p>(ii) <math>90v \frac{dv}{dx} = 90g - \frac{1}{40}gv^2</math>  <math>\int \frac{90v}{90g - \frac{1}{40}gv^2} dv = \int dx</math>  <math>-\frac{1800}{g} \ln \left  90g - \frac{1}{40}gv^2 \right  = x + c_1</math>  <math>90g - \frac{1}{40}gv^2 = Ae^{-\frac{gx}{1800}}</math>  <math>v^2 = \frac{40}{g} \left( 90g - Ae^{-\frac{gx}{1800}} \right)</math>  <math>x = 0, v = 0 \Rightarrow A = 90g</math>  <math>v^2 = 3600 \left( 1 - e^{-\frac{gx}{1800}} \right)</math></p>	<p>M1 N2L                      A1                      M1 Separate and integrate                      A1 LHS                      M1 Rearrange, dealing properly with constant                      M1 Use condition                      E1 Complete argument</p>	7
<p>(iii) WD against <math>R = \int_0^{1800} kv^2 dx</math>  <math>= \int_0^{1800} 90g \left( 1 - e^{-\frac{gx}{1800}} \right) dx</math>  <math>= \left[ 90g \left( x + \frac{1800}{g} e^{-\frac{gx}{1800}} \right) \right]_0^{1800}</math>  <math>= 162000(g + e^{-2} - 1)</math>  <math>x = 1800 \Rightarrow v^2 = 3600(1 - e^{-2})</math>                      Loss in energy  <math>= 90g \cdot 1800 - \frac{1}{2} \cdot 90 \cdot 3600(1 - e^{-2})</math>  <math>= 162000(g + e^{-2} - 1) = \text{WD against } R</math></p>	<p>B1                      M1 Integrate                      A1                      B1                      M1 GPE                      M1 KE                      E1 Convincingly shown (including signs)</p>	7
<p>(iv) <math>v = 60\sqrt{1 - e^{-2}} \approx 59.9983</math></p>	<p>B1</p>	1
<p>(v) <math>90 \frac{dv}{dt} = 90g - 90v</math>  <math>\int \frac{dv}{g - v} = \int dt \quad \left[ \text{or } \int_{59.9983}^{10} \frac{dv}{g - v} = \int_0^t dt \right]</math>  <math>-\ln g - v  = t + c_1</math>  <math>t = 0, v = 59.9983 \Rightarrow c_1 = -3.91598</math>  <math>v = 10 \Rightarrow t = -\ln 0.2 + 3.91598</math>  <math>\approx 5.53 \text{ s}</math></p>	<p>M1 N2L                      A1                      M1 Separate and integrate                      A1                      M1 Use condition (or limits)                      M1 Calculate <math>t</math>                      A1</p>	7

1(i)			
	$(m -  \delta m )(v + \delta v) +  \delta m (v - u) - mv = -mg\delta t$	M1	Impulse = change in momentum
		A1	Accept sign errors in $\delta m$
	$m\delta v - u \delta m  -  \delta m \delta v = -mg\delta t$		
	$m\frac{\delta v}{\delta t} + u\frac{\delta m}{\delta t} + \delta m\frac{\delta v}{\delta t} = -mg$	M1	Form DE
	$\Rightarrow m\frac{dv}{dt} + u\frac{dm}{dt} = -mg$	E1	Complete argument (including signs)
			4
(ii)	$\frac{dm}{dt} = -k \Rightarrow m = m_0 - kt$	M1	
	So $(m_0 - kt)\frac{dv}{dt} - uk = -(m_0 - kt)g$	A1	
	$\frac{dv}{dt} = \frac{uk}{m_0 - kt} - g$		
	$v = \int \left( \frac{uk}{m_0 - kt} - g \right) dt$	M1	Integrate
	$= -u \ln(m_0 - kt) - gt + c$	A1	
	$t = 0, v = 0 \Rightarrow 0 = -u \ln m_0 + c$	M1	Use condition
	$v = -u \ln \left( 1 - \frac{k}{m_0} t \right) - gt$	A1	
	Fuel burnt when $m_0 - kt = 0.25m_0$	M1	
	$v = -u \ln 0.25 - \frac{0.75m_0 g}{k}$	A1	
			8

4764

Mark Scheme

June 2010

2(i)	$m \frac{dv}{dt} = -mkv^{\frac{3}{2}}$ $\int -v^{-\frac{3}{2}} dv = \int k dt$ $2v^{-\frac{1}{2}} = kt + c$ $t = 0, v = 25 \Rightarrow c = \frac{2}{5}$ $2v^{-\frac{1}{2}} = kt + \frac{2}{5}$ $v = 4 \left( kt + \frac{2}{5} \right)^{-2}$	M1 A1 M1 A1 M1 M1 E1	N2L  Separate and integrate  Use condition  Rearrange	7
(ii)	$x = \int 4 \left( kt + \frac{2}{5} \right)^{-2} dt$ $= -\frac{4}{k} \left( kt + \frac{2}{5} \right)^{-1} + A$ $t = 0, x = 0 \Rightarrow A = \frac{10}{k}$ $x = \frac{1}{k} \left( 10 - \frac{4}{kt + \frac{2}{5}} \right)$	M1 M1 A1	Integrate  Use condition	3
(iii)	<p>The speed decreases, tending to zero</p> <p>The displacement tends to <math>\frac{10}{k}</math></p>	B1 B1	Cv (10/k)	2

3(i)	$V = -mga \sin \theta + \frac{\lambda}{2(2a)} (3a \sin \theta)^2$	M1	GPE term
		M1	EPE term
		A1	
	$\frac{dV}{d\theta} = -mga \cos \theta + \frac{\lambda}{4a} \cdot 9a^2 \cdot 2 \sin \theta \cdot \cos \theta$	M1	Differentiate
		A1	
	$= a \cos \theta \left( \frac{9}{2} \lambda \sin \theta - mg \right)$	E1	
			6
(ii)	$\frac{dV}{d\theta} = 0 \Leftrightarrow \cos \theta = 0$ or $\sin \theta = \frac{2mg}{9\lambda}$	M1	Solve $\frac{dV}{d\theta} = 0$
(A)	$\lambda > \frac{2}{9} mg$		
	$\theta = \frac{\pi}{2}$	A1	
	and $\theta = \sin^{-1} \frac{2mg}{9\lambda}$	A1	
	$\frac{d^2V}{d\theta^2} = -a \sin \theta \left( \frac{9}{2} \lambda \sin \theta - mg \right) + a \cos \theta \left( \frac{9}{2} \lambda \cos \theta \right)$	M1	Second derivative (or other valid method)
		A1	Any correct form
	$= a \left( \frac{9}{2} \lambda (1 - 2 \sin^2 \theta) + mg \sin \theta \right)$		
	$V'' \left( \frac{\pi}{2} \right) = a \left( -\frac{9}{2} \lambda + mg \right) < 0$	M1	Substitute $\theta = \frac{\pi}{2}$
	$\Rightarrow$ unstable	A1	Deduce unstable
	$V'' \left( \sin^{-1} \left( \frac{2mg}{9\lambda} \right) \right) = a \left( \frac{9}{2} \lambda \left( 1 - 2 \left( \frac{2mg}{9\lambda} \right)^2 \right) + \frac{2(mg)^2}{9\lambda} \right)$	M1	Substitute other value

4764

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June 2010

	$= \frac{9}{2} \lambda a \left( 1 - \left( \frac{2mg}{9\lambda} \right)^2 \right)$		
	$\lambda > \frac{2}{9} mg \Rightarrow \left( \frac{2mg}{9\lambda} \right)^2 < 1 \Rightarrow V'' > 0$	M1	Consider second derivative
	$\Rightarrow \text{stable}$	A1	Complete argument
			10
(B)	$\lambda < \frac{2}{9} mg \Rightarrow$	M1	Consider solutions
	$\theta = \frac{\pi}{2} \text{ only}$	A1	
	$V'' \left( \frac{\pi}{2} \right) = a \left( -\frac{9}{2} \lambda + mg \right) > 0$	M1	Consider second derivative
	$\Rightarrow \text{stable}$	A1	Complete argument
			4
(C)	$\lambda = \frac{2}{9} mg \text{ gives } \theta = \frac{1}{2} \pi \text{ only (from both factors)}$	M1	Consider solutions
		A1	
	$V'' \left( \frac{\pi}{2} \right) = 0$		
	$V' \left( \frac{\pi}{2} - \epsilon \right) = (+)(-) = (-)$		
	$V' \left( \frac{\pi}{2} + \epsilon \right) = (-)(+) = (+)$	M1	Valid method
	Hence stable	A1	Complete argument
			4



4(i)	Mass of slice $\approx \rho \pi y^2 \delta x$	M1	
	So $I_{\text{slice}} \approx \frac{1}{2} (\rho \pi y^2 \delta x) y^2$	M1	
	$= \frac{1}{32} \rho \pi x^4 \delta x$	A1	
	So $I_{\text{cone}} \approx \int_0^{2a} \frac{1}{32} \rho \pi x^4 dx$	M1	
	$= \left[ \frac{1}{160} \rho \pi x^5 \right]_0^{2a}$	A1	ft
	$= \frac{1}{5} \pi \rho a^5$	A1	
	$\rho = \frac{M}{\frac{2}{3} \pi a^3}$	M1	
	$\Rightarrow I_{\text{cone}} = \frac{3}{10} M a^2$	E1	
			8
(ii)	Mass of small cone $= \left(\frac{1}{2}\right)^3 M = \frac{1}{8} M$		
	Mass of frustum $= \frac{7}{8} M$	B1	
	$I_{\text{large cone}} = I_{\text{small cone}} + I$	M1	
	$\frac{3}{10} M a^2 = \frac{3}{10} \left(\frac{1}{8} M\right) \left(\frac{1}{2} a\right)^2 + I$	M1	Moment of inertia of small cone
	$\Rightarrow I = \frac{93}{320} M a^2$		
	$\frac{7}{8} M = 2.8, a = 0.1 \Rightarrow I = 0.0093$	E1	
			4

4764

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June 2010

<p>(iii) <math>C = I\bar{\theta} \Rightarrow \bar{\theta} = \frac{0.05}{0.0093}</math></p> <p><math>t = \frac{10}{\bar{\theta}} = 1.86</math></p>	<p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p>	<p>4</p>
<p>(iv) Centre of mass:</p> <p><math>\frac{7}{8}M\bar{x} + \frac{1}{8}M \cdot \frac{3a}{4} = M \cdot \frac{3a}{2}</math></p> <p><math>OG = \bar{x} = \frac{45a}{28} = \frac{4.5}{28} \approx 0.1607</math></p> <p>i.e. G is <math>\frac{1.7}{28} \approx 0.0607</math> m from the small circular face</p>	<p>M1</p> <p>A1</p> <p>A1     Any distance which locates G</p>	<p>3</p>
<p>(v) <math>0.1J = I(10 - 5)</math></p> <p><math>J = 0.465</math></p> <p>Radius at G is <math>\frac{1}{2}\bar{x}</math></p> <p><math>\left(\frac{4.5}{56}\right)J = I(5 - \omega)</math></p> <p><math>\Rightarrow \omega = \frac{55}{56} \approx 0.98</math></p>	<p>M1     Moment of impulse = ang. momentum</p> <p>A1</p> <p>B1</p> <p>M1     Moment of impulse = ang. momentum</p> <p>A1</p>	<p>5</p>

4764

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June 2011

1(i) $\frac{dm}{dt} = -\lambda m \Rightarrow m = m_0 e^{-\lambda t}$	M1 A1	2
(ii) $\frac{d}{dt}(mv) = mg - kmv$ $\frac{dm}{dt}v + m\frac{dv}{dt} = mg - kmv$ $-\lambda mv + m\frac{dv}{dt} = mg - kmv$ $\frac{dv}{dt} = g + (\lambda - k)v$ $\int \frac{dv}{g + (\lambda - k)v} = \int dt$ $\frac{1}{\lambda - k} \ln(g + (\lambda - k)v) = t + c$ $g + (\lambda - k)v = Ae^{(\lambda - k)t}$ $v = 0, t = 0 \Rightarrow A = g$ $v = \frac{g}{\lambda - k} (e^{(\lambda - k)t} - 1)$ AG	B1 N2L M1 Expand derivative M1 Substitute A1 M1 Separate and integrate A1√ M1 Use condition E1 Convincingly shown	8
(iii) $mv = \frac{1}{2}m_0 \Rightarrow e^{-\lambda t} = \frac{1}{2}$ $\Rightarrow t = \frac{1}{\lambda} \ln 2$ $v = \frac{g}{\lambda - k} \left( 2^{\frac{\lambda - k}{\lambda}} - 1 \right)$	M1 Accept substituted into their expression in part (i) A1 Any correct form	2
2(i) $V = \frac{1}{2}k(2a - x - a)^2 + \frac{1}{2}k(\sqrt{a^2 + x^2} - a)^2$  $\frac{dV}{dx} = -k(a - x) + k(\sqrt{a^2 + x^2} - a) \cdot 2x \cdot \frac{1}{2}(a^2 + x^2)^{-1/2}$ $= -k(a - x) + kx \left( 1 - \frac{a}{\sqrt{a^2 + x^2}} \right)$ $= 2kx - ka - \frac{kax}{\sqrt{a^2 + x^2}}$ AG	M1 for $E = \frac{1}{2}kx^2$ A1 A1 M1 E1 Convincingly shown	5
(ii) $\frac{d^2V}{dx^2} = 2k - \frac{ka\sqrt{a^2 + x^2} - kax \cdot x(a^2 + x^2)^{-3/2}}{a^2 + x^2}$ $= 2k - \frac{ka^3}{(a^2 + x^2)^{3/2}}$ $(a^2 + x^2)^{3/2} > (a^2)^{3/2} = a^3$ $\Rightarrow \frac{ka^3}{(a^2 + x^2)^{3/2}} < k \Rightarrow V''(x) > 2k - k > 0$	M1 A1 M1 E1 Convincingly shown	4
(iii) $x = \frac{1}{2}a \Rightarrow V' = ka - ka - \frac{ka \cdot \frac{1}{2}a}{\sqrt{a^2 + (\frac{1}{2}a)^2}} < 0$ $x = a \Rightarrow V' = 2ka - ka - \frac{ka^2}{\sqrt{a^2 + a^2}} = ka - \frac{ka}{\sqrt{2}} > 0$ Hence (as $V'$ continuous) $V' = 0$ between $\frac{1}{2}a$ and $a$ . So equilibrium. Stable as $V'' > 0$ .	M1 E1 Convincingly shown B1	3

<p>3(i) <math>800v \frac{dv}{dx} = \frac{8v^4}{v} - 8v^2</math></p> <p><math>\int \frac{100dv}{v^2-v} = \int dx</math></p> <p><math>\int 100 \left( \frac{1}{v-1} - \frac{1}{v} \right) dx = \int dx</math></p> <p><math>100(\ln(v-1) - \ln v) = x + c</math></p> <p><math>x = 0, v = 2 \Rightarrow c = -100 \ln 2</math></p> <p><math>100 \ln \left( \frac{2(v-1)}{v} \right) = x</math></p> <p><math>v = 20 \Rightarrow x = 100 \ln \left( 2 \times \frac{19}{20} \right) = 100 \ln 1.9</math></p> <p><math>\frac{2(v-1)}{v} = e^{0.01x}</math></p> <p><math>2v - 2 = ve^{0.01x}</math></p> <p><math>v = \frac{2}{2 - e^{0.01x}}</math></p>	<p>M1 N2L with <math>P/v</math></p> <p>A1</p> <p>M1 Separate</p> <p>M1 Partial fractions</p> <p>A1</p> <p>M1 Use condition</p> <p>A1 AEF, condone <math>m</math></p> <p>E1</p> <p>M1 Rearrange</p> <p>A1 Cao without <math>m</math></p>	10
<p>(ii) <math>\frac{dx}{dt} = \frac{2}{2 - e^{0.01x}}</math></p> <p><math>\int (2 - e^{0.01x}) dx = \int 2 dt</math></p> <p><math>2x - 100e^{0.01x} = 2t + c_2</math></p> <p><math>x = 0, t = 0 \Rightarrow c_2 = -100</math></p> <p><math>2x - 100e^{0.01x} = 2t - 100</math></p> <p><math>x = 100 \ln 1.9 \Rightarrow t \approx 19.2</math> AG</p>	<p>M1</p> <p>M1 Separate and integrate</p> <p>A1</p> <p>M1 Use condition</p> <p>A1 Any correct form</p> <p>E1</p>	6
<p>(iii) <math>800 \frac{dv}{dt} = -8v^2</math></p> <p><math>\int 100v^{-2} dv = \int -1 dt</math></p> <p><math>-100v^{-1} = -t + c_3</math></p> <p><math>t = 19.2, v = 20 \Rightarrow -5 = -19.2 + c_3</math></p> <p><math>c_3 = 14.2</math></p> <p><math>v = \frac{100}{t - 14.2}</math></p> <p><math>2 = \frac{100}{t - 14.2} \Rightarrow t = 64.2</math></p>	<p>M1 N2L</p> <p>A1</p> <p>M1 Separate and integrate</p> <p>A1</p> <p>M1 Use condition</p> <p>M1 Rearrange</p> <p>A1 CAO</p> <p>B1 Accept <math>t = 45</math> (time for this part of motion)</p>	8

4(i) $I_K = \frac{1}{2}my^2$ $2I_{\text{diameter}} = I_K$ $I_{\text{diameter}} = \frac{1}{4}my^2$ $I = \frac{1}{4}my^2 + mx^2$ $= m\left(\frac{1}{4}\left(\frac{1}{2}x\right)^2 + x^2\right)$ $= \frac{17}{16}mx^2$ AG	B1 M1 Use perpendicular axes theorem B1 M1 Use parallel axes theorem M1 Use $y = \frac{1}{2}x$ E1 Complete argument	6
(ii) Mass of slice $\approx M\left(\frac{\pi y^2 \delta x}{\frac{1}{2}\pi a^2 \cdot 1a}\right)$ $= \frac{2M}{a^2}y^2 \delta x$ $I_{\text{slice}} \approx \frac{17}{16}\left(\frac{2M}{a^2}y^2 \delta x\right)x^2$ $= \frac{17M}{16a^2}x^4 \delta x$ $I = \int_0^{2a} \frac{17M}{16a^2}x^4 dx$ $= \frac{17M}{16a^2}\left[\frac{1}{5}x^5\right]_0^{2a}$ $= \frac{81}{20}Ma^2$ AG	M1 B1 Deal correctly with mass/density M1 A1 M1 Substitute for $y$ M1 A1 E1 Complete argument	8
(iii) $\frac{1}{2}I\dot{\theta}^2 - Mg \cdot \frac{5}{2}a \cos \theta = -Mg \cdot \frac{5}{2}a \cos \alpha$ $\dot{\theta}^2 = \frac{2Mga}{I}(\cos \theta - \cos \alpha)$ $= \frac{20g}{17a}(\cos \theta - \cos \alpha)$	M1 Energy equation B1 Position of centre of mass A1 KE term F1 GPE terms ft their CoM only E1 Complete argument	5
(iv) $2\dot{\theta}\ddot{\theta} = -\frac{20g}{17a}\sin \theta \dot{\theta}$ $\ddot{\theta} = -\frac{10g}{17a}\sin \theta$ $\approx -\frac{10g}{17a}\theta$ for small $\theta$ Hence SHM Period $2\pi\sqrt{\frac{17a}{10g}}$	M1 Differentiate or use $I\ddot{\theta} = \text{torque}$ A1 M1 Use $\sin \theta \approx \theta$ E1 B1	5

4764

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June 2012

Question		Answer	Marks	Guidance
1	(i)	$mv = (m + \delta m)(v + \delta v) + (-\delta m)(v - u) \quad (\text{note } \delta m < 0)$ $mv = mv + v\delta m + m\delta v + \delta m\delta v - v\delta m + u\delta m$ $m \frac{\delta v}{\delta t} + u \frac{\delta m}{\delta t} + \delta m \frac{\delta v}{\delta t} = 0$ $m \frac{dv}{dt} = -u \frac{dm}{dt}$ $\frac{dm}{dt} = -k$ $m = m_0 - kt$ $(m_0 - kt) \frac{dv}{dt} = uk$	M1 A1  M1   B1 B1 E1 <b>[6]</b>	Attempt at momentum equation Condone wrong sign of $\delta m$  Simplify and divide by $\delta t$   SOI All correct including sign of $\delta m$
1	(ii)	$\int dv = \int \frac{uk}{m_0 - kt} dt$ $v = -u \ln(m_0 - kt) + c$ $t = 0, v = v_0 \Rightarrow v_0 = -u \ln m_0 + c$ $c = v_0 + u \ln m_0$ $v = v_0 + u \ln \left( \frac{m_0}{m_0 - kt} \right)$	M1 A1 M1 A1 A1 <b>[5]</b>	Separate and integrate  Use condition aef
2	(i)	Let equilibrium extension be $e$ $mv \frac{dv}{dx} = mg - k(e + x)$ At equilibrium, $mg = ke$ So $mv \frac{dv}{dx} = -kx$	M1 A1 B1 E1 <b>[4]</b>	N2L All terms correct oe With evidence of working

4764

Mark Scheme

June 2012

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2	(ii)	$\int mv \, dv = \int -kx \, dx$ $\frac{1}{2}mv^2 = -\frac{1}{2}kx^2 + c$ $x = a, v = 0 \Rightarrow 0 = -\frac{1}{2}ka^2 + c$ $\frac{1}{2}mv^2 = \frac{1}{2}k(a^2 - x^2)$ $v = -\sqrt{\frac{k}{m}(a^2 - x^2)}$ <p>(<math>v &lt; 0</math> when moving up)</p>	M1 A1 M1 A1 E1  [5]	Solutions from SHM acceptable  oe  AG Complete argument including justification for square root.
2	(iii)	$\int \frac{1}{\sqrt{a^2 - x^2}} \, dx = \int -\sqrt{\frac{k}{m}} \, dt$ $\arcsin\left(\frac{x}{a}\right) = -\sqrt{\frac{k}{m}}t + c_2$ $x = a, t = 0 \Rightarrow \frac{1}{2}\pi = c_2$ $x = a \sin\left(\frac{1}{2}\pi - \sqrt{\frac{k}{m}}t\right) = a \cos\left(\sqrt{\frac{k}{m}}t\right)$	M1*  A1 DM1  A1  [4]	Solutions from SHM <i>NOT</i> acceptable  Accept $c_2 = \arcsin 1$  Either form
3	(i)	$l = 2a \sin \theta$ $V = \frac{\lambda}{2a}(2a \sin \theta - a)^2$ $\dots + mga \cos 2\theta$ $\frac{dV}{d\theta} = -2mga \sin 2\theta + \frac{\lambda}{a}(2a \sin \theta - a) \cdot 2a \cos \theta$ $= -4mga \sin \theta \cos \theta + 2\lambda a \cos \theta (2 \sin \theta - 1)$ $= 2a \cos \theta (2\lambda \sin \theta - 2mg \sin \theta - \lambda)$	M1 A1 M1 A1  M1 M1 E1 [7]	OE eg $a\sqrt{2 - 2\cos 2\theta}$ EPE OE eg $\frac{\lambda}{2a}(a\sqrt{2 - 2\cos 2\theta} - a)^2$ Both terms GPE OE eg $mga \sin(\frac{1}{2}\pi - 2\theta)$  Differentiate  Use trigonometric identities as necessary

4764

Mark Scheme

June 2012

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3	(ii)	$\theta = \frac{1}{2}\pi \Rightarrow \frac{dV}{d\theta} = 0 \times (\dots) = 0$ <p>hence equilibrium</p> $\frac{d^2V}{d\theta^2} = -2a \sin \theta (2\lambda \sin \theta - 2mg \sin \theta - \lambda)$ $+ 2a \cos \theta (2\lambda \cos \theta - 2mg \cos \theta)$ $\theta = \frac{1}{2}\pi \Rightarrow \frac{d^2V}{d\theta^2} = -2a(2\lambda - 2mg - \lambda)$ <p>So <math>\lambda &lt; 2mg \Rightarrow \frac{d^2V}{d\theta^2} &gt; 0 \Rightarrow</math> stable</p> <p>If <math>\cos \theta \neq 0</math></p> $\frac{dV}{d\theta} = 0 \Leftrightarrow 2\lambda \sin \theta - 2mg \sin \theta - \lambda = 0$ $\Leftrightarrow \sin \theta = \frac{\lambda}{2\lambda - 2mg}$ <p>But <math>\lambda &lt; 2mg \Rightarrow 2\lambda - 2mg &lt; \lambda</math>  <math>\Rightarrow \sin \theta &gt; 1</math> or <math>\sin \theta &lt; 0</math>            So no valid solutions</p>	M1 E1  M1 A1  M1  E1   M1  M1 E1 <b>[9]</b>	  Here or in (iii) or use sign method  Use $V''$ or equivalent method   Consider other solutions  Attempt at showing not valid Must consider both ends
3	(iii)	<p>If <math>\lambda &gt; 2mg, \theta = \frac{1}{2}\pi</math> as before</p> <p><math>V'' &lt; 0</math> so unstable</p> <p>or <math>\sin \theta = \frac{\lambda}{2\lambda - 2mg}</math></p> <p>and <math>\frac{1}{2} &lt; \frac{\lambda}{2\lambda - 2mg} &lt; 1</math> so gives valid solution</p> $\theta = \sin^{-1}\left(\frac{\lambda}{2\lambda - 2mg}\right) \text{ or } \pi - \sin^{-1}\left(\frac{\lambda}{2\lambda - 2mg}\right)$ <p>and <math>V'' = 0 + 2a \cos^2 \theta (2\lambda - 2mg)</math>  <math>= (+ve)(+ve)</math> so stable (in both cases)</p>	B1 B1 E1 E1 B1 M1 A1 <b>[7]</b>	    For both



4764

Mark Scheme

June 2012

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4	(i)	$\delta I = 2\pi r \delta r \rho r^2$ $\rho = \frac{m}{\pi a^2}$ $I_{\text{disc}} = \int_0^a \frac{m}{2a^2} r^3 dr$ $= \frac{m}{2a^2} \left[ \frac{1}{4} r^4 \right]_0^a$ $= \frac{1}{2} m a^2$	B1 B1 M1 M1 A1 E1 <b>[6]</b>	for $k \int r^3 dr$ $k \left[ \frac{1}{4} r^4 \right]_0^a$ with limits $\frac{k}{4} a^4$
4	(ii)	$I = m_1 a^2 + \frac{1}{2} m a^2 \times 2$ $m = M \frac{\pi a^2}{2\pi a^2 + 2\pi a h}$ $m_1 = M \frac{2\pi a h}{2\pi a^2 + 2\pi a h}$ $\text{So } I = M a^2 \left( \frac{\pi a^2 + 2\pi a h}{2\pi a^2 + 2\pi a h} \right)$ $I = \frac{1}{2} M a^2 \left( \frac{a + 2h}{a + h} \right)$	M1 M1 B1 B1 M1 E1 <b>[6]</b>	Curved surface $2\pi h \rho a^3$ Combine $+ \frac{1}{2} \rho \pi a^4 \times 2$ $m = \pi \rho a^2$ $m_1 = 2\pi a h \rho$ Substitute $I = M \frac{\pi \rho a^4 + 2\pi \rho a^3}{2\pi \rho a^2 + 2\pi \rho a h}$
4	(iii)	$I = \frac{1}{2} \times 8 \times 0.5^2 \left( \frac{0.5 + 0.6}{0.5 + 0.3} \right) = 1.375$ $I(\omega - 0) = J a$ $1.375 \omega = 55 \times 0.5$ $\omega = 20 \text{ rad s}^{-1}$	B1 M1 A1 <b>[3]</b>	Impulse/momentum

4764

Mark Scheme

June 2012

Question		Answer	Marks	Guidance
4	(iv)	$I \frac{d\dot{\theta}}{dt} = -2\dot{\theta}^2$ $\int 1.375 \dot{\theta}^{-2} d\dot{\theta} = \int -2 dt$ $-\frac{1.375}{\dot{\theta}} = -2t + c$ $t = 0, \dot{\theta} = 20 \Rightarrow c = -0.06875$ $t = 5 \Rightarrow -\frac{1.375}{\dot{\theta}} = -10 - 0.06875$ $\Rightarrow \dot{\theta} = 0.137 \text{ (3sf)}$	B1 M1 M1 A1 M1 M1 A1 [7]	Separate Integrate Use condition
4	(v)	$I \left( \frac{-0.137}{t} \right) = -0.03$ $t = 6.26 \text{ s}$	M1 A1 A1 [3]	Complete method with correct acceleration (or both sides +ve) awfw [6.25, 6.3] CAO

4764

Mark Scheme

June 2013

Question		Answer	Marks	Guidance	
1	(i)	$\frac{dm}{dt} = k \Rightarrow m = kt + c$ conditions $\Rightarrow m = m_0 + kt$ $\left( \frac{d}{dt}(mv) = 0 \Rightarrow \right) \quad mv = m_0 v_0$ $v = \frac{m_0 v_0}{m} = \frac{m_0 v_0}{m_0 + kt}$ $x = \int \frac{m_0 v_0}{m_0 + kt} dt$ $= \frac{m_0 v_0}{k} \ln(m_0 + kt) \quad (+ c_2)$ conditions $\Rightarrow 0 = \frac{m_0 v_0}{k} \ln m_0 + c_2$ so $x = \frac{m_0 v_0}{k} (\ln(m_0 + kt) - \ln m_0)$ $= \frac{m_0 v_0}{k} \ln \left( \frac{m_0 + kt}{m_0} \right) = \frac{m_0 v_0}{k} \ln \left( 1 + \frac{kt}{m_0} \right)$	B1 B1 M1 A1 A1 M1 A1 M1 E1 <b>[9]</b>	Momentum equation Integrate their expression for v Use initial conditions	Or derive a differential equation in only two variables
1	(ii)	$kt = 2m_0 \Rightarrow t = \frac{2m_0}{k} \Rightarrow v = \frac{1}{3} v_0$ $x = \frac{m_0 v_0}{k} \ln 3$	B1 B1 <b>[2]</b>	Follow through their $v = f(t)$ Ft	<b>SC</b> If $kt = m_0$ Award B1 either correct on follow through
2	(i)	$BC = 2 \times 0.5 \sin \frac{1}{2} \theta$	E1 <b>[1]</b>		

4764

Mark Scheme

June 2013

Question		Answer	Marks	Guidance
2	(ii)	$V = -0.5g \cdot 0.25 \sin \theta +$ $\frac{1}{2} \cdot 2(BC - 0.5)^2 + \frac{1}{2} \cdot 2(BD - 0.5)^2$ $BD^2 = 1^2 + 0.5^2 - 2 \times 1 \times 0.5 \cos \theta = 1.25 - \cos \theta$ $V = -1.225 \sin \theta + (\sin \frac{1}{2} \theta - 0.5)^2 +$ $(\sqrt{1.25 - \cos \theta} - 0.5)^2$ $\frac{dV}{d\theta} = -1.225 \cos \theta + 2(\sin \frac{1}{2} \theta - 0.5)(\frac{1}{2} \cos \frac{1}{2} \theta) +$ $2(\sqrt{1.25 - \cos \theta} - 0.5) \left( \frac{\sin \theta}{2\sqrt{1.25 - \cos \theta}} \right)$ $= -1.225 \cos \theta + \sin \frac{1}{2} \theta \cos \frac{1}{2} \theta - 0.5 \cos \frac{1}{2} \theta +$ $\sin \theta - \frac{0.5 \sin \theta}{\sqrt{1.25 - \cos \theta}}$ $= 1.5 \sin \theta - 1.225 \cos \theta - \frac{0.5 \sin \theta}{\sqrt{1.25 - \cos \theta}} - 0.5 \cos \frac{1}{2} \theta$	M1 M1 B1 A1 M1 M1 A1 E1 <b>[8]</b>	GPE At least one EPE term oe Differentiate Use of chain rule one EPE term correct Complete argument
2	(iii)	$\theta \approx 1.2$ and $4.1$ Stable and unstable respectively at $\theta \approx 1.2$ , $\frac{dV}{d\theta}$ increasing because the graph shows that $f'(\theta)$ is positive so $V$ minimum hence stable at $\theta \approx 4.1$ $\frac{dV}{d\theta}$ decreasing because the graph shows that $f'(\theta)$ is negative, so max. so unstable	B1 B1 M1 A1 <b>[4]</b>	Both Allow B1M1A1 from 1.1 and/or 4.05 Consider gradient, relating $f$ to $\frac{dV}{d\theta}$ Clear evidence from the graph

4764

Mark Scheme

June 2013

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3	(i)	$2 \frac{dv}{dt} = \frac{2v^3 + 4v}{v} - 6v$ $\frac{dv}{dt} = v^2 - 3v + 2 = (1-v)(2-v)$ $\int \frac{1}{(1-v)(2-v)} dv = \int dt$ $\int \left( \frac{1}{1-v} - \frac{1}{2-v} \right) dv = \int dt$ $-\ln 1-v  + \ln 2-v  = t + c$ $t = 0, v = 0 \Rightarrow \ln 2 = c$ $t = \ln(2-v) - \ln(1-v) - \ln 2$ $= \ln \frac{2-v}{2(1-v)}$	M1 A1 E1 M1 M1 A1 A1 M1 M1 E1 <b>[10]</b>	N2L Separate Partial fractions LHS RHS Use condition Rearrange
3	(ii)	$\Rightarrow \frac{2-v}{2(1-v)} = e^t \Rightarrow 2-v = 2e^t - 2e^t v$ $v = \frac{2(e^t - 1)}{2e^t - 1}$	M1 A1 <b>[2]</b>	Rearrange
3	(iii)	$v = 0.8 \Rightarrow P = 2 \times 0.8^3 + 4 \times 0.8 = 4.224$ $t = \ln \frac{2-0.8}{2(1-0.8)} = \ln 3 \approx 1.10$	E1 B1 <b>[2]</b>	

Question		Answer	Marks	Guidance
3	(iv)	$2 \frac{dv}{dt} = \frac{4.224}{v} - 6v$ $\int \frac{2}{\frac{4.224}{v} - 6v} dv = \int dt$ $\int \frac{v}{2.112 - 3v^2} dv = \int dt$ $-\frac{1}{6} \ln  2.112 - 3v^2  = t + c_2$ $2.112 - 3v^2 = Ae^{-6t}$ $t = \ln 3, v = 0.8 \Rightarrow 2.112 - 3 \times 0.8^2 = Ae^{-6 \ln 3}$ $A = 139.968$ $v = \sqrt{0.704 - 46.656e^{-6t}}$ $t \rightarrow \infty \Rightarrow v \rightarrow \sqrt{0.704} \approx 0.839$	<p>B1</p> <p>M1</p> <p>M1</p> <p>A1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>A1</p> <p>[10]</p>	<p>N2L</p> <p>Separate</p> <p>LHS</p> <p>RHS</p> <p>Use condition to find constant</p> <p>Rearrange to make <math>v</math> the subject</p> <p>Correct</p> <p>Ft their expression for <math>v</math></p> <p><b>Alternate</b></p> <p><math>t \rightarrow \infty \Rightarrow 2.112 - 3v^2 \rightarrow 0</math></p>
4	(i)	$\rho = \frac{m}{\frac{1}{2}a^2 \cdot \frac{\pi}{3}}$ <p>element with radius <math>x</math> and 'width' <math>\delta x</math> :</p> $\delta m = \rho x \frac{\pi}{3} \delta x \Rightarrow \delta I = \rho x \frac{\pi}{3} \delta x \cdot x^2$ $= \frac{2m}{a^2} x^3 \delta x$ $I = \int_0^a \frac{2m}{a^2} x^3 dx$ $= \frac{2m}{a^2} \left[ \frac{x^4}{4} \right]_0^a$ $= \frac{2m}{a^2} \left( \frac{a^4}{4} \right) = \frac{1}{2} ma^2$	<p>B1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>E1</p> <p>[6]</p>	<p>Or let <math>\rho = 1</math> without lose of generality</p> <p>Ft their <math>\rho</math></p> <p>Integrate</p>

4764

Mark Scheme

June 2013

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4	(ii)	$\frac{2a}{\pi}$	B1 [1]		
4	(iii)	$\frac{1}{2} I \dot{\theta}^2 - mg \left( \frac{2a}{\pi} \right) \cos \theta = -mg \left( \frac{2a}{\pi} \right) \cos \frac{2}{3} \pi$ OE  $\frac{1}{2} m a^2 \dot{\theta}^2 = 2mg \left( \frac{2a}{\pi} \right) \left( \cos \theta + \frac{1}{2} \right)$  $\dot{\theta}^2 = \frac{4g}{\pi a} (2 \cos \theta + 1)$	M1 A1 A1  E1 [4]	Energy Two correct terms All correct	RHS: or $mg \left( \frac{2a}{\pi} \right) \cos \frac{1}{3} \pi$
4	(iv)	Max $\dot{\theta}$ when $\cos \theta = 1$ $\Rightarrow \dot{\theta}^2 = \frac{12g}{\pi a}$ Speed max. furthest from axis, so max speed $= a \sqrt{\frac{12g}{\pi a}} = \sqrt{\frac{12ag}{\pi}}$	M1 A1 M1 A1 [4]	oe	
4	(v)	$2\ddot{\theta} \dot{\theta} = \frac{4g}{\pi a} (-2 \sin \theta \dot{\theta})$  $\ddot{\theta} = -\frac{4g}{\pi a} \sin \theta$	M1 A1 [2]	Differentiate with respect to time Or use $C = I \ddot{\theta}$	May be seen in (iv)  May be seen in (iv)
4	(vi)	$J \cdot x = \pm I \cdot \frac{1}{2} \omega \pm I \cdot \omega$ $J \cdot \frac{3}{4} a = \frac{1}{2} m a^2 \left( \frac{1}{2} \omega \right) - \frac{1}{2} m a^2 (-\omega)$  $\theta = (-)\frac{1}{3} \pi \Rightarrow \omega^2 = \frac{4g}{\pi a} \left( 2 \left( \frac{1}{2} \right) + 1 \right) \Rightarrow \omega = \sqrt{\frac{8g}{\pi a}}$  $J = m \sqrt{\frac{8ag}{\pi}}$	M1 A1 B1 A1 [4]		

4764

Mark Scheme

June 2013

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4	(vii)	$\frac{1}{2} I \left( \frac{1}{2} \sqrt{\frac{8g}{\pi a}} \right)^2 - mg \left( \frac{2a}{\pi} \right) \cos \frac{1}{3} \pi = -mg \left( \frac{2a}{\pi} \right) \cos \theta$ $\Rightarrow \theta = \cos^{-1} \frac{1}{4} \approx 1.32$	M1 A1 A1 [3]	CAO